



Features

- 2KHz speed loop bandwidth
- 17-bit absolute encoder
- EtherCAT bus servo support 125 μs synchronization period
- Adapt to multiple mainstream controllers
- Compact volume design meets the installation requirements of demanding spaces
- One click download and FOE function to improve production efficiency
- High quality motor bearings extend service life
- Stable operation in harsh environments

Applications

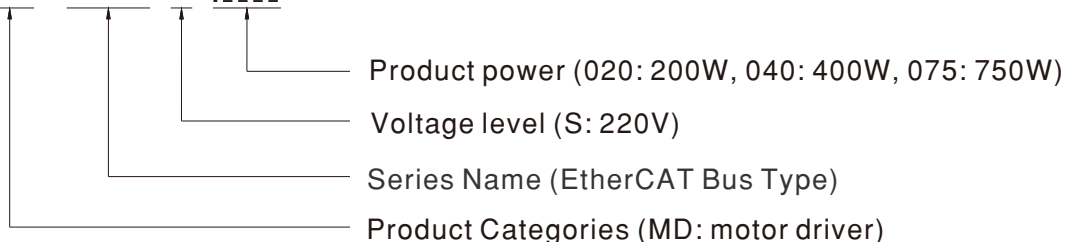
- Precision CNC Machine Tools
- Industrial Robots
- Semiconductor Manufacturing
- Intelligent Logistics Systems
- Automotive Manufacturing

Description

The MD-730N series drive, as a standard drive solution tailored for industrial fields such as 3C electronics, photovoltaic new energy, battery manufacturing, and intelligent packaging, achieves rapid and seamless integration with control systems through its embedded EtherCAT industrial bus and multi-protocol communication interfaces. By adopting new-generation power devices and innovative designs, it significantly reduces the overall space required while greatly enhancing the flexibility of drive system layouts. With superior performance and multiple advanced functionalities, it creates faster, more stable, and more precise driving scenarios, ensuring worry-free production and delivering high-efficiency productivity for your enterprise.

Drive Model Encoding

MD - 730 N S -040





Bus-Type Servo Drive System

MD-730N series

| Specification | | MD-730NS-020 | MD-730NS-040 | MD-730NS-075 |
|-------------------------------------|--------------------------------|--|---|---------------------------|
| Data | | | | |
| Driver power | | 0.2KW | 0.4KW | 0.75KW |
| OUTPUT | Continuous output current | 1.6A | 2.8A | 5.5A |
| | Maximum output current | 5.8A | 10.1A | 16.9A |
| INPUT | Main circuit power supply | Single-phase 200~240VAC, $\pm 10\%$, 50/60Hz | | |
| | Control circuit power supply | Powered up by the bus, sharing one power supply and rectification part with the main circuit | | |
| Braking capability | | External braking resistor | | Built-in braking resistor |
| Control mode | | IGBT PWM control, sine wave current drive mode 220 V, 380 V: Single-phase or three-phase full-bridge rectification | | |
| Encoder feedback | | 17-bit multi-turn absolute encoder, which can be used as a single-turn absolute encoder in absence of the battery | | |
| Communication Protocol | | EtherCAT | | |
| Position control | | | | |
| Position reference | | The network-based instruction source is Ether CAT,PROFINET | | |
| Supporting signal allocation change | | P-OT (positive limit switch), N-OT (negative limit switch), HomeSwitch (home switch) TouchProbe1 (probe 1), TouchProbe2 (probe 2) | | |
| Supporting signal allocation change | | 3 Dos Load capacity: 50 mA Voltage range: 5 V to 30 V | | |
| Speed/torque control | | | | |
| Speed control range | | 1:6000 (The lower limit is the threshold within which the servo drive keeps running with the rated torque load.) | | |
| Speed reference input | | Source of network-type references: EtherCAT communication | | |
| Torque reference input | | | | |
| Environment | | | | |
| Operating temperature | | 0~55°C | | |
| Storage temperature | | -40~70°C | | |
| IP rating | | IP20 | | |
| SAFETY & EMC | | | | |
| SAFETY STANDARDS | | IEC 61800-5-1:2007; AMD1:2016 | | |
| EMC EMISSION | Parameter | Standard | Test Level / Note | |
| | Conducted Emissions | EN IEC61800-3 | Class A | |
| | Radiated Emissions | EN IEC61800-3 | Class A | |
| | Voltage flicker | EN 61000-3-11 IEC 61000-3-11 | ----- | |
| EMC IMMUNITY | Parameter | Standard | Test Level / Note | |
| | ESD | IEC 61800-3, 61000-6-7 | Level 3, 8KV air ; Level 2; 4KV contact | |
| | EFT | IEC 61800-3, 61000-6-7 | Level 2, 1KV | |
| | Radiated | IEC 61800-3, 61000-6-7 | | |
| | Surge | IEC 61800-3, 61000-6-7 | Level ± 2 KV/Line2KV/Line ± 4 KV/Line Earth | |
| | Conducted | IEC 61800-3, 61000-6-7 | 0.15 ~ 230MHz, 10V 80% AM(1KHz) | |
| | THD | IEC 61800-3, 61000-6-7 | 12% | |
| | Individual Harmonic orders | IEC 61800-3, 61000-6-7 | Class 3 | |
| | Voltage Dips and Interruptions | IEC 61800-3, 61000-6-7 | Class 3 0,40%,70%,80% | |
| OTHERS | | | | |
| PACKING | | 0.78kg | 1.04kg | |
| DIMENSION | | 40*161*150mm | 50*161*174mm | |

MD-K Series Servo Motor



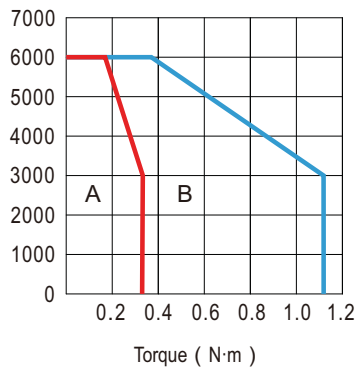
Motor Model Encoding

MD - K S 2 6 S 3C;04

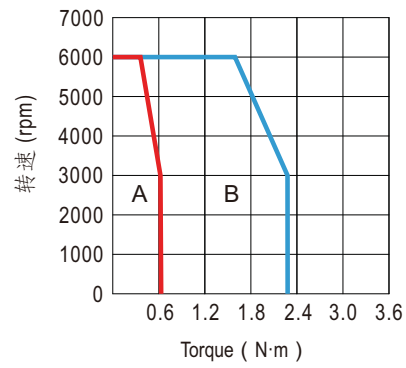
- Power level (01:100W,02: 200W,04:400W,08:750W)
- Rated speed (3C: 3000rpm,C:*10³)
- Brake and oil seal specification
(N: no brake and oil sealing; S: no brake, with oil seal;
C: with brake.no oil sealing; E:with brake and oil sealing)
- Shaft end specification (6: straight shaft, with keyway, threaded)
- Encoder type (2: 17 bit multi turn absolute value magnetic encoder)
- Voltage level (S:220V)
- Series Name
- Product Categories (MD: motor driver)

MD-K Motor Torque Speed Characteristics

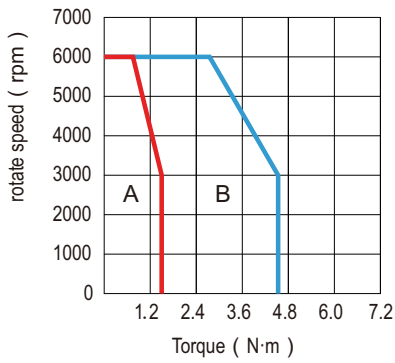
● 100W(40 frame)



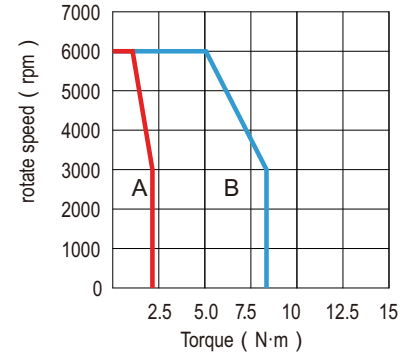
● 200W(60 frame)



● 400W(60 frame)



● 750W(80 frame)



A — Continuous work area
B — Short-term work area

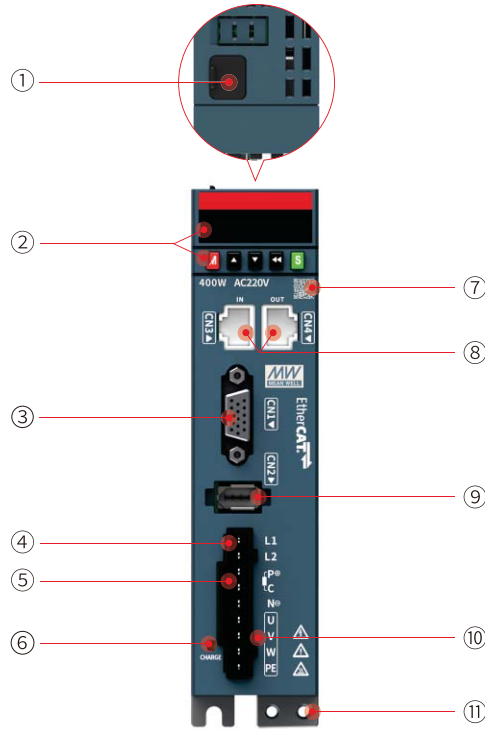


| Specification | MD-KS26N3C01 | MD-KS26C3C01 | MD-KS26S3C02 | MD-KS26E3C02 |
|--|--------------------------------------|------------------------------------|--|----------------------------|
| Technical Specifications | | | | |
| Rated power (W) | 100 | | 200 | |
| Rated current (A) | 1.1 | | 1.29 | |
| Maximum current (A) | 3.9 | | 4.41 | |
| Rated torque (N·m) | 0.32 | | 0.64 | |
| Maximum torque (N·m) | 1.12 | | 2.23 | |
| Rotor inertia (10 kg ⁴ m ²) | 0.03 | 0.033 | 0.34 | 0.35 |
| Overload multiplier | 3.5 | | | |
| Rated speed (rpm) | 3000 | | | |
| Maximum speed (rpm) | 6000 | | | |
| Flange size | 40 | | 60 | |
| Rated voltage (V) | 220 | | | |
| Weight (kg) | 0.4 | 0.6 | 0.8 | 1.2 |
| General Specifications | | | | |
| Duty | S1 (Continuous) | | | |
| Vibration class | V15 | | | |
| Thermal class | Level F | | | |
| Insulation resistance | 500VDC, above 10MΩ | | | |
| Excitation mode | Permanent magnetic | | | |
| Mounting mode | Flange | | | |
| Insulation voltage | 1500 V AC, 1 minute (220 V level) | | | |
| Braking and maintenance | no brake and oil sealing | with brake.no oil sealing | no brake, with oil seal | with brake and oil sealing |
| Safety & EMC | | | | |
| SAFETY STANDARDS | IEC 60034-1:2022 | | | |
| EMC EMISSION | Parameter | Standard | Test Level/Note | |
| | Conducted Disturbance | EN IEC 61000-6-4:2019 | Class A | |
| | Radiated Electromagnetic Disturbance | EN IEC 61000-6-4:2019 | Class A | |
| EMC IMMUNITY | Parameter | Standard | Test Level/Note | |
| | ESD | EN 61000-4-2:2009 | Level 3,8KV air; Level 2,4KV contact | |
| | RF EM-Fields | EN 61000-4-3:2006+ A1:2008+A2:2010 | Level 2,10V/m | |
| | Fast Transients | EN 61000-4-4:2012 | Level 6KV | |
| | Surge | EN 61000-4-5:2014 | Level 2,1KV/Line to Line; Level 3,2KV/Line-Earth | |
| | Injected Currents | EN 61000-4-6:2014 | Level 2,3Vrms/m | |
| Environment | | | | |
| Ambient temperature | 0~40°C (Non-freezing) | | | |
| Ambient humidity | 20%~80% (Non-condensing) | | | |
| Storage temperature | -20~+60°C (Non-freezing) | | | |
| Storage environment | 20%~80% (Non-condensing) | | | |
| Insulation resistance | 500VDC, above 10MΩ | | | |
| Shock resistance | 490m/s ² (5G) | | | |
| Vibration resistance | 49m / s ² (10G) | | | |



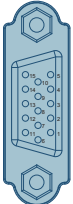
| Specification | MD-KS26S3C04 | MD-KS26E3C04 | MD-KS26S3C08 | MD-KS26E3C08 |
|--|--------------------------------------|------------------------------------|--|----------------------------|
| Technical Specifications | | | | |
| Rated power (W) | 400 | | 750 | |
| Rated current (A) | 2.51 | | 4.60 | |
| Maximum current (A) | 8.78 | | 16.30 | |
| Rated torque (N·m) | 1.27 | | 2.39 | |
| Maximum torque (N·m) | 4.45 | | 8.36 | |
| Rotor inertia (10 kg ⁴ m ²) | 0.59 | 0.60 | 1.72 | 1.77 |
| Overload multiplier | 3.5 | | | |
| Rated speed (rpm) | 3000 | | | |
| Maximum speed (rpm) | 6000 | | | |
| Flange size | 60 | | 80 | |
| Rated voltage (V) | 220 | | | |
| Weight (kg) | 1.1 | 1.5 | 2.2 | 2.8 |
| General Specifications | | | | |
| Duty | S1 (Continuous) | | | |
| Vibration class | V15 | | | |
| Thermal class | Level F | | | |
| Insulation resistance | 500VDC, above 10MΩ | | | |
| Excitation mode | Permanent magnetic | | | |
| Mounting mode | Flange | | | |
| Insulation voltage | 1500 V AC, 1 minute (220 V level) | | | |
| Braking and maintenance | no brake, with oil seal | with brake and oil sealing | no brake, with oil seal | with brake and oil sealing |
| Safety & EMC | | | | |
| SAFETY STANDARDS | IEC 60034-1:2022 | | | |
| EMC EMISSION | Parameter | Standard | Test Level/Note | |
| | Conducted Disturbance | EN IEC 61000-6-4:2019 | Class A | |
| | Radiated Electromagnetic Disturbance | EN IEC 61000-6-4:2019 | Class A | |
| EMC IMMUNITY | Parameter | Standard | Test Level/Note | |
| | ESD | EN 61000-4-2:2009 | Level 3,8KV air; Level 2,4KV contact | |
| | RF EM-Fields | EN 61000-4-3:2006+ A1:2008+A2:2010 | Level 2,10V/m | |
| | Fast Transients | EN 61000-4-4:2012 | Level 6KV | |
| | Surge | EN 61000-4-5:2014 | Level 2,1KV/Line to Line; Level 3,2KV/Line-Earth | |
| | Injected Currents | EN 61000-4-6:2014 | Level 2,3Vrms/m | |
| Environment | | | | |
| Ambient temperature | 0~40°C (Non-freezing) | | | |
| Ambient humidity | 20%~80% (Non-condensing) | | | |
| Storage temperature | -20~+60°C (Non-freezing) | | | |
| Storage environment | 20%~80% (Non-condensing) | | | |
| Insulation resistance | 500VDC, above 10MΩ | | | |
| Shock resistance | 490m/s ² (5G) | | | |
| Vibration resistance | 49m / s ² (10G) | | | |

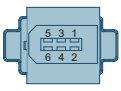
Interface Description








| NO. | Name | NO. | Name |
|-----|---|-----|--|
| ① | Commissioning and communication port(CN6) | ⑦ | QR code on machine |
| ② | Display and operation area | ⑧ | EtherCAT communication network port (CN3)(CN4) |
| ③ | Control signal port(CN1) | ⑨ | Encoder signal port (CN2) |
| ④ | Power input | ⑩ | Motor power output |
| ⑤ | Braking resistor port | ⑪ | System ground |
| ⑥ | Charging indicator | | |

Terminal Definition

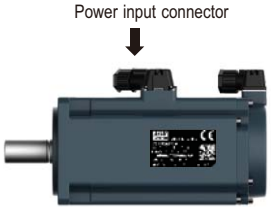
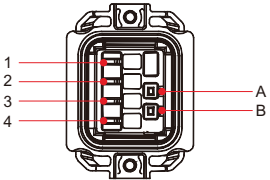

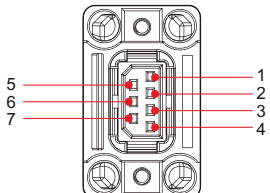
| Terminal | Pin | Illustrate | |
|--|------|------------|--|
|  <p>CN1 user control terminal</p> | 10 | DI1 | Positive limit switch |
| | 9 | DI2 | Negative limit switch |
| | 8 | DI3 | Home switch |
| | 7 | DI4 | Probe 2 |
| | 11 | DI5 | Probe 1 |
| | 15 | +24V | Internal 24 V power supply, Voltage range: 20~28V, Max. output current: 150 mA |
| | 14 | COM- | (Note: A resettable fuse is shared with the CNS STO function terminals, with a total current limit of 150mA) |
| | 13 | COM+ | Common terminal of DI terminals |
| | 1 | DO1+ | Servo ready |
| | 6 | DO1- | |
| | 3 | DO2+ | Fault |
| | 2 | DO2- | |
| | 5 | DO3+ | Brake |
| 4 | DO3- | | |

| Terminal | Pin | Illustrate | |
|---|-----------|------------|-----------------|
|  <p>CN2 encoder terminal</p> | 1 | +5V | 5V power supply |
| | 2 | 0V | - |
| | 3 | Reserved | - |
| | 4 | Reserved | - |
| | 5 | PS+ | Encoder signal |
| | 6 | PS- | |
| | Enclosure | PE | Shield |

| Ether communication terminals | Pin | Illustrate | | |
|--|--|------------|-----------------|-----------------|
|  <p>CN4</p>  | 1 | TD+ | Data transmit + | |
| | 2 | TD- | Data transmit - | |
| | 3 | RD+ | Data receive + | |
| | 4/5 | - | - | |
| | 6 | RD- | Data receive - | |
| | 7/8 | - | - | |
| |  <p>CN3</p>  | 9 | TD+ | Data transmit + |
| | | 10 | TD- | Data transmit - |
| 11 | | RD+ | Data receive + | |
| 12/13 | | - | - | |
| 14 | | RD- | Data receive - | |
| 15/16 | | - | - | |

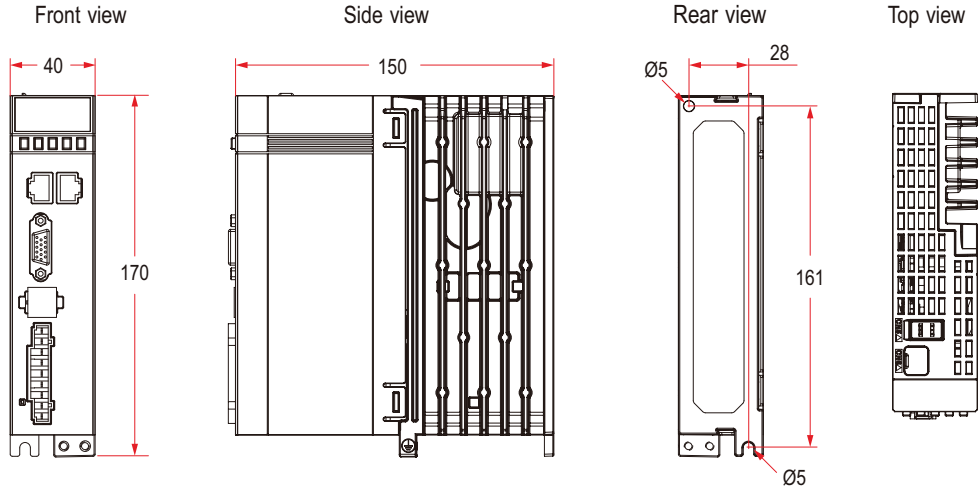
| Terminal | Pin | Illustrate |
|--|--------|--|
|  CN6 commissioning and communication | Type-C | Use a USB cable or serial cable (two sections of wiring: Type-C to serial, serial to US8) to connect the drive to the PC |

General specifications

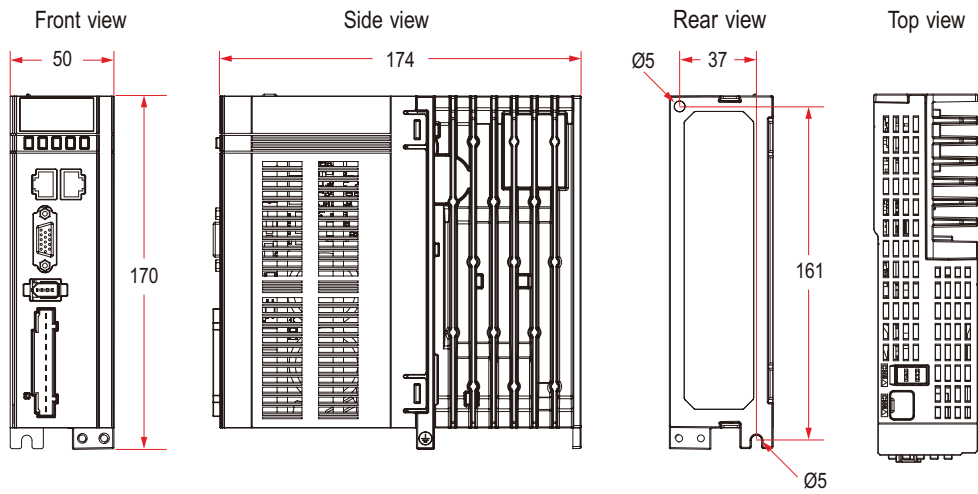
| Cable Type | Terminal Layout (Cable Side) | Pin No. | Usage |
|---|---|---------|-------------------------------|
|  <p>Power input connector</p> |  | 1 | Phase V |
| | | 2 | Phase U |
| | | 3 | Phase W |
| | | 4 | Grounding cable |
| | | A | Brake (polarity insensi-tive) |
| | | B | Brake (polarity insensi-tive) |
|  <p>Encoder connector</p> |  | 1 | DATA+ |
| | | 2 | DATA- |
| | | 3 | BAT+ |
| | | 4 | BAT- |
| | | 5 | +5V |
| | | 6 | 0V |
| | | 7 | Enclosure |

Mechanism Dimension

- 200W/400W



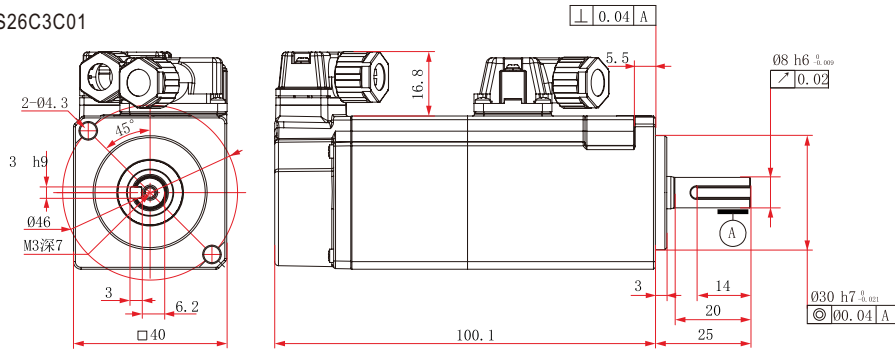
- 750W



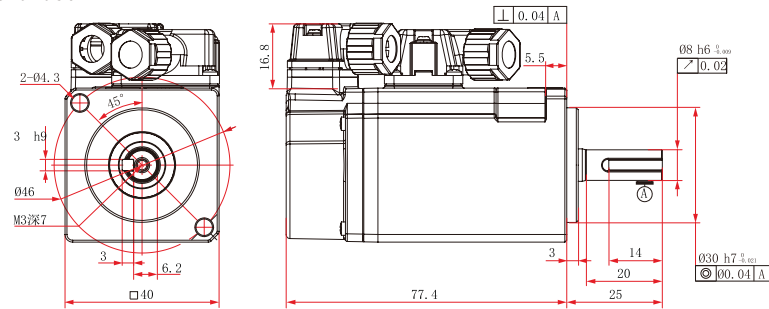
Mechanism Dimension

● 100W(40 frame)

MD-KS26C3C01

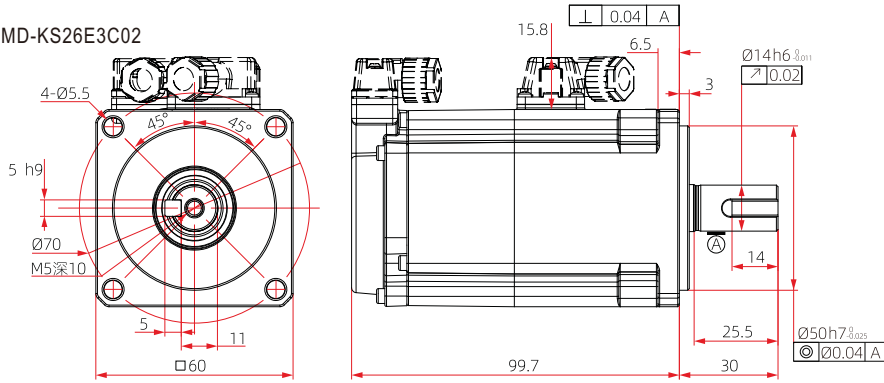


MD-KS26N3C01

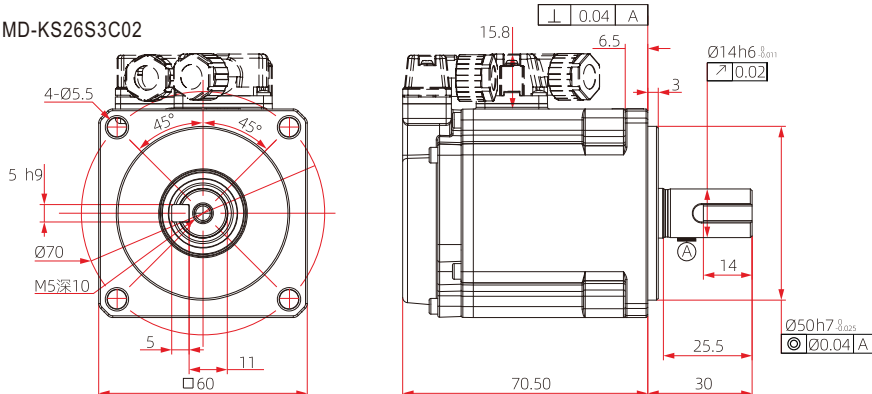


● 200W(60 frame)

MD-KS26E3C02

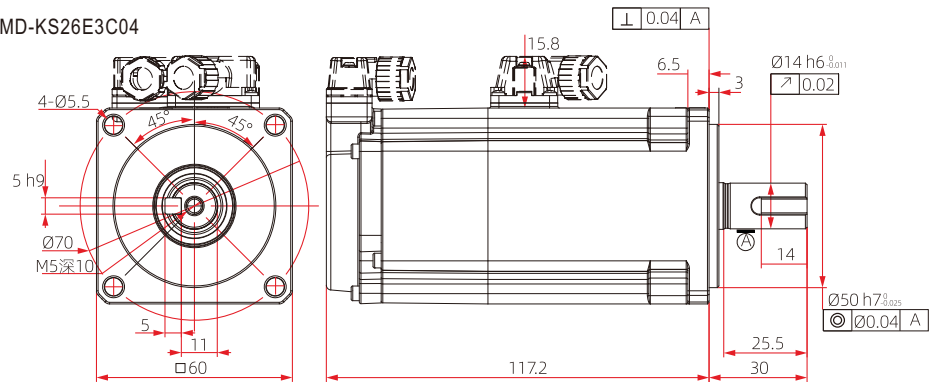


MD-KS26S3C02

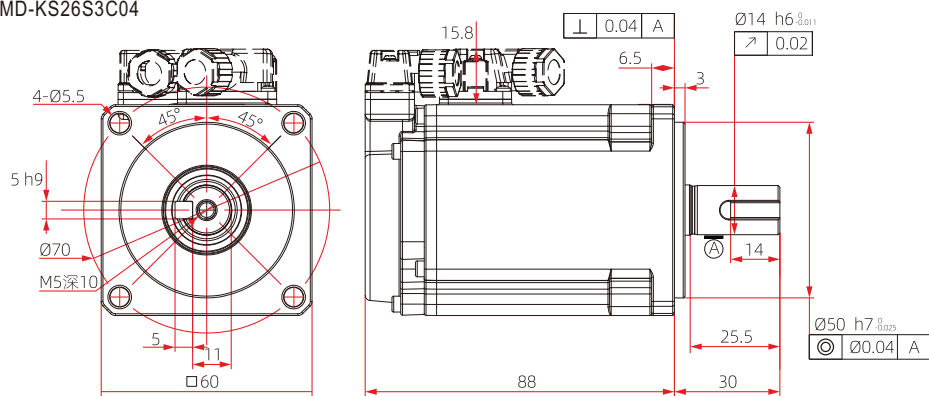


● 400W(60 frame)

MD-KS26E3C04

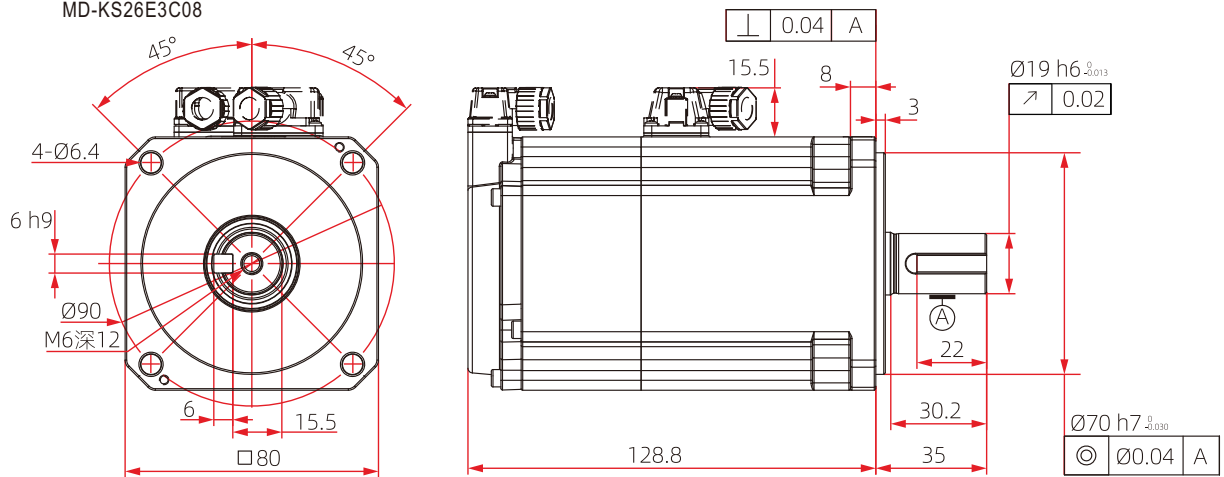


MD-KS26S3C04

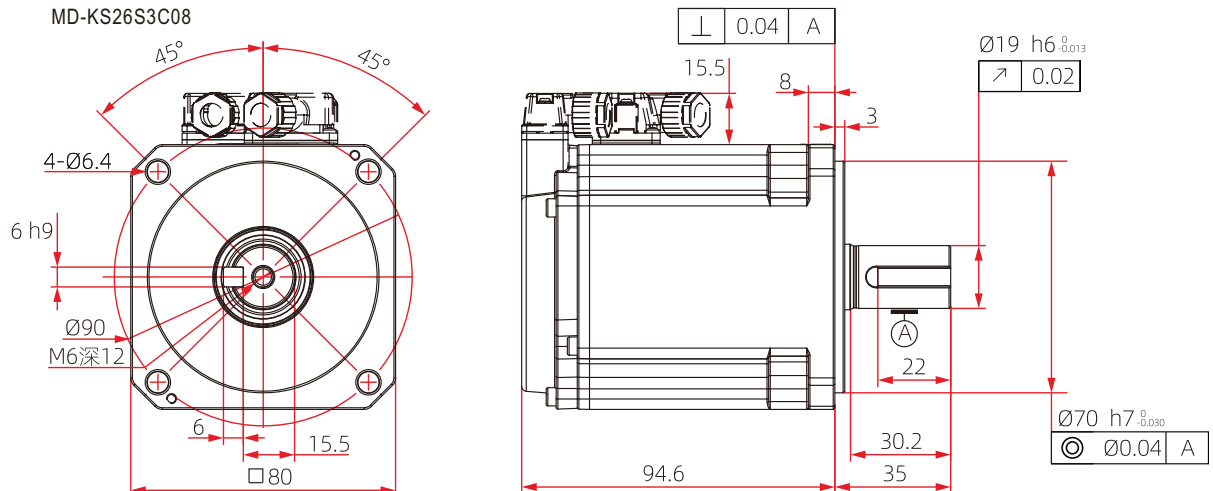


● 750W(80 frame)

MD-KS26E3C08



MD-KS26S3C08



Product Selection

Driver & Motor Configuration Relationship

| Driver Model | Motor model | Motor adaptation accessories | | Brake Type |
|--------------|--------------|------------------------------|---------------------|---------------|
| | | Power cable model | Encoder cable model | |
| MD-730NS-020 | MD-KS26N3C01 | ① | ③④ | without brake |
| | MD-KS26C3C01 | ② | | with brake |
| | MD-KS26S3C02 | ① | | without brake |
| | MD-KS26E3C02 | ② | | with brake |
| MD-730NS-040 | MD-KS26S3C04 | ① | ③④ | without brake |
| | MD-KS26E3C04 | ② | | with brake |
| MD-730NS-075 | MD-KS26S3C08 | ① | ③④ | without brake |
| | MD-KS26E3C08 | ② | | with brake |

Cable Information (to be ordered separately)

| Name | Model | Length | Exterior drawing | number |
|--|-----------------|---------|------------------------|--------|
| Power Line | MD-PWCR0-3/5/10 | 3/5/10m | | ① |
| Power Line | MD-PWCB0-3/5/10 | 3/5/10m | | ② |
| Encoder line | MD-ENCC2-3/5/10 | 3/5/10m | | ③ |
| Encoder Line (Without Battery Housing) | MD-ENCC1-3/5/10 | 3/5/10m | | ④ |
| Servo drive 100 Gigabit pass Signal network cable | MD-NET-0.3/3 | 0.3/3m | | |
| DB15 Terminal fittings | MD-DB15 | --- | <p>Welded surfaces</p> | |
| DB44 Terminal fittings | MD-DB44 | --- | <p>Welded surfaces</p> | |

Note: If you have other model needs, please contact MEAN WELL dealers.